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Application Number 10597673

Filing Date 2006-08-03

First Named Inventor Moshe Shoham

Art Unit N/A

Examiner Name Not Yet Assigned

Attorney Docket Number 20763/0205292-US0

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	1	Parenti-Castelli et al., "Closed-Form Solution of the Direct Kinematics of the 6-3 Type Stewart Platform Using One Extra Sensor," Kulwer Acedemic Publishers (1996)						
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	J-P. Merlet, "Determination of the presence of singularities in a workspace volume of a parallel manipulator," NATO-ASI, Computational methods in mechanism.							
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	5	R. Ben-Horin, "Design Parameters of Parallel Manipulators," The Technion, Israel (1998)						
	6	H. Bamberger et al., "Kinematic structure of a parallel robot for MEMS fabrication," Advances in Robot Kinematics, ARK, Italy (2004)						
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